YIBO LIU

buaayorklau@gmail.com
Personal Webpage | Google Scholar
https://github.com/York-SDCNLab | LinkedIn

Research Interest

My research interest lies in the domain of **3D computer vision, and image & video generation**.
2025-Present: Working on World Foundation Models (Cosmos and Sora-like Video Generation).
2023-2025: Have been conducting research on MMLLM, Vision Question Answering (VQA), and Diffusion Models intending to generate photorealistic 2D/3D assets. I had one first-author paper, VQA-Diff, accepted to **ECCV2024**.
2024-2025: Worked on embodied AI. I had one first-author paper (HIPPo) submitted to **RA-L**.
2022-2024: Worked on 3D modeling and 3D content (NeRFs/3D Gaussians Splatting) generation. I had one first-author paper, MV-DeepSDF, accepted to **ICCV2023** and one co-first authored paper accepted to NeurIPS 2024 Workshop.
2020-2025: Worked on robotic vision. My research centered on the localization and navigation of robots (RA-L2022, IROS2022, TIM2025).

Research Experience

Epson America Apr. 2025 - Present
Research Scientist *Toronto, Canada*

- Focused on applied research on **World Foundation Models** (e.g., Cosmos) and **Vison Language Models**.

Huawei Noah's Ark Lab Jun. 2022 - Feb. 2025
Associate Researcher (Internship) *Toronto, Canada*

- Focused on in-the-wild object reconstruction and image/text-to-3D content generation under the background of simulation in the autonomous driving industry. My research involved Visual Question Answering models, Diffusion models, NeRFs, and Gaussian Splatting.
- Contribution:
  VQA-Diff: Exploiting VQA and Diffusion for Zero-Shot Image-to-3D Vehicle Asset Generation in Autonomous Driving **(first author, ECCV2024)**, DOI.
  MV-DeepSDF: Implicit Modeling with Multi-Sweep Point Clouds for 3D Vehicle Reconstruction in Autonomous Driving (**first author**, **ICCV2023**), DOI.
  Top-3 winner of OmniObject3D challenge (Co-first author, ArXiv, **NeurIPS 2024 Workshop on Symmetry and Geometry in Neural Representations**).

York University Jan. 2020 – Jan. 2025
Teaching Assistant. & Graduate Research Assistant. *Toronto, Canada*

- Focused on robotic vision which involved camera/LiDAR-based perception, SLAM, and navigation.
- Contribution:
  Intensity Image-based LiDAR Fiducial Marker System (first author, **RA-L2022**, DOI, Github **60** stars) .
  Application of Ghost-DeblurGAN to Fiducial Marker Detection (first author, **IROS2022**, DOI, Github **42** stars).
  Mapping and Localization using LiDAR Fiducial Markers (first author, accepted to **TIM2025**, DOI, Github **120** stars).

Education

York University, Lassonde School of Engineering Toronto, Canada
Ph.D. Supervisor:Prof. Jinjun Shan. *Jan 2020-Jan 2025*

- Scholarship:
  Academic Excellence Fund (maximum amount, 2000$, 2022&2023).
  York Graduate Scholarship (2020).

BeiHang University, School of Aeronautic Science and Engineering Beijing, China
Master *Sep 2017-Jan 2020*

- Scholarship:
  First-class Academic Merit (Top 3%).
  Outstanding Science and Technology Competition Medal of May 4th (5 out of 22,000).
  Ministry of Industry and Information Technology Innovation and Entrepreneurship (10 out of 40,000)

BeiHang University, School of Aeronautic Science and Engineering Beijing, China
Bachelor *Sep 2013-June 2017*

- Scholarship:
  Outstanding Graduate (Top 5%);
  Outstanding Student Cadres

Selected Publication & Award List

Publication

[1]**Liu Y***, Yang Z*, Wu G, Ren Y, Lin K, Liu B, Liu Y, Shan J. "VQA-Diff: Exploiting VQA and Diffusion for Zero-Shot Image-to-3D Vehicle Asset Generation in Autonomous Driving", in Proc. European Conference on Computer Vision (**ECCV**), 2024, pp. 323-340.

[2]**Liu Y**, Zhu K, Wu G, Ren Y, Liu B, Liu Y, Shan J. "MV-DeepSDF: Implicit Modeling with Multi-Sweep Point Clouds for 3D Vehicle Reconstruction in Autonomous Driving", in Proc. IEEE/CVF International Conference on Computer Vision (**ICCV**), 2023, pp. 8306-8316.

[3]**Liu Y**, Shan J, Haridevan A, Zhang S. "L-PR: Exploiting LiDAR Fiducial Marker for Unordered Low Overlap Multiview Point Cloud Registration", IEEE Transactions on Instrumentation and Measurement (**TIM**), 2025, doi: 10.1109/TIM.2025.3544745

[4]Yang Z*, **Liu Y***, Wu G, Cao T, Ren Y, Liu Y, Liu B. "Learning Effective NeRFs and SDFs Representations with 3D Generative Adversarial Networks for 3D Object Generation". **NeurIPS 2024** Workshop on Symmetry and Geometry in Neural Representations. Top-3 winner of **ICCV 2023** OmniObject3D Challenge.

[5]**Liu Y**, Schofield H, Shan J. "Intensity Image-Based LiDAR Fiducial Marker System", in IEEE Robotics and Automation Letters (**RA-L**), vol. 7, no. 3, pp. 6542-6549, July 2022, doi: 10.1109/LRA.2022.3174971.

[6]**Liu Y**, Haridevan A, Shan J. "Application of Ghost-DeblurGAN to Fiducial Marker Detection", in Proc. IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS**), 2022, pp. 6827-6832, doi: 10.1109/IROS47612.2022.9981701.

[7]**Liu Y**, Schofield H, Shan J. "Navigation of a Self-Driving Vehicle Using One Fiducial Marker", in Proc. IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI), 2021, pp. 1-6, doi: 10.1109/MFI52462.2021.9591194.

[8]Zhang S, Shan J and **Liu Y** "Approximate Inference Particle Filtering for Mobile Robot SLAM," in IEEE Transactions on Automation Science and Engineering, doi: 10.1109/**TASE**.2024.3475735

[9]Zhang S, Shan J and **Liu Y**. "Variational Bayesian Estimator for Mobile Robot Localization With Unknown Noise Covariance," in IEEE/ASME Transactions on Mechatronics, vol. 27, no. 4, pp. 2185-2193, Aug. 2022, doi: 10.1109/**T-MECH**.2022.3161591.

Award

[1]**Top-3 winner** of OmniObject3D Challenge at **ICCV2023** (3D Object Generation Task).

[2]The first prize, 15th 'Challenge Cup' National Science and Technology College of extra-curricular academic competition works, second author

[3]Excellent Grade, 9th National College Students Innovation and Entrepreneurship Training Plan, initiator

Technical Reviewer

Conferences: ICLR, NeurIPS, AISTATS, ICRA, IROS, AIM, ICPR
Journals: RA-L, RA-M, RAS, TIE, TIM